

BSL ROBOT GRIPPER AND SERVOS (BSL-GRIPKIT)

This Robot Gripper with 2 x Robot Servos is used for the EMG-Controlled Robotic Arm created with [BSL PRO Lesson Set H40](#) (10 labs).

- The two Servo motors are used in tandem to perform “twist” and “grasp” movements to manipulate objects with the gripper.
- The potentiometer is used to optimize robotic control for each student’s unique EMG output. The potentiometer is easily accessed since the circuit board is separate from the motor.
- The servos can control the gripper to open to 3.3 cm (1.3”) from closed and can rotate the gripper approximately 180 degrees. A Phillips screwdriver is required for assembly. It also includes two clamp cushions that adhere to the inner sides of the gripper.
- Both motors use Pulse Width Control.
- The output shaft is supported on the bottom and top with bronze bushings and the potentiometer is indirect drive.

BSL-GRIPKIT is included in BSLBME-ROBOT-HW, BSLBME-ROBOT-TA, and BSL-BME-ARM-TA.

Servo Specifications:

Control System:	+Pulse Width Control 1500 usec Neutral
Required Pulse:	3-5 V Peak to Peak Square Wave
Operating Voltage:	4.8-6.0 V
Operating Temperature Range:	-20 to +60 Degree C
Operating Speed (4.8 V):	0.21 sec/60° at no load
Operating Speed (6.0 V):	0.16 sec/60° at no load
Stall Torque (4.8 V):	45.82 oz/in. (3.3 kg/cm)
Stall Torque (6.0 V):	56.93 oz/in. (4.1 kg/cm)
Operating Angle:	45° one side pulse traveling 400 usec
360 Modifiable:	Yes
Direction:	Clockwise/Pulse Traveling 1500 to 1900 usec
Current Drain (4.8 V):	8 mA/idle and 150 mA no load operating
Current Drain (6.0 V):	8.8 mA/idle and 180 mA no load operating
Dead Band Width:	8 usec
Motor Type:	3 Pole Ferrite
Potentiometer Drive:	Indirect Drive
Bearing Type:	Dual Oilite Bushing
Gear Type:	Nylon
Connector Wire Length:	11.81" (300 mm=11.81 in)
Dimensions:	See Schematics
Weight:	1.6 oz (45.5 g)

Gripper Specifications:

Max clamp width:	3.3 cm (1.3")
Size:	57 x 65 x 30 mm (2.24"x 2.56"x 1.18")
Weight:	25 g